

# Multimodal Ocular Biometrics Approach: A Feasibility Study

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## Abstract

*Growing efforts have been concentrated on the development of alternative biometric recognition strategies, the intended goal to increase the accuracy and counterfeit-resistance of existing systems without increased cost. In this paper, we propose and evaluate a novel biometric approach using three fundamentally different traits captured by the same camera sensor. Considered traits include: 1) the internal, non-visible, anatomical properties of the human eye, represented by Oculomotor Plant Characteristics (OPC); 2) the visual attention strategies employed by the brain, represented by Complex Eye Movement patterns (CEM); and, 3) the unique physical structure of the iris. Our experiments, performed using a low-cost web camera, indicate that the combined ocular traits improve the accuracy of the resulting system. As a result, the combined ocular traits have the potential to enhance the accuracy and counterfeit-resistance of existing and future biometric systems.*

## 1. Introduction

Biometric systems are becoming increasingly more important to advance security in a wide variety of applications, including everyday computer access, health care, information systems, e-commerce, and border control. Multimodal biometric systems often rely on traits such as iris pattern, fingerprints, face, hand geometry, and voice [1]. While the security potential of biometric techniques is high, unsolved security challenges continue to escalate with recent technological advances that allow the production of high quality artifacts [2] and sophisticated spoofing mechanisms [3].

Multimodal biometric systems often provide increased accuracy of identification and resistance to spoofing in comparison to single-trait systems [1]; however, these benefits come at the expense of decreased usability and increased cost, due largely to the employment of multiple sensors and additional steps in the data acquisition process.

In this work, we investigate the feasibility of a multimodal ocular biometrics approach which uses the infor-

mation from three fundamentally different physiological and behavioral traits, and requires the use of only a single image sensor and an array of infrared (IR) lights. Considered traits include: 1) the internal, non-visible, anatomical properties of the human eye, represented by Oculomotor Plant Characteristics (OPC); 2) the visual attention strategies employed by the brain, represented by Complex Eye movement patterns (CEM); and, 3) the unique physical structure of the iris. OPC and CEM traits are inferred from the dynamics of eye movements derived from the sequence of eye images captured by the sensor, while the iris pattern is extracted directly from the same images. The combination of accurate static traits, such as iris patterns, and highly dynamic traits, such as eye movements, has the potential to provide a high degree of identification accuracy and counterfeit-resistance to the underlying system.

This work contributes to the state-of-the-art by: 1) investigating the performance of both individual and combined CEM-, OPC-, and iris-based biometrics on a single, low-cost image sensor; 2) generate the largest existing eye movement database for biometric research.

This paper is organized as follows: Section 2 discusses the state-of-the-art in related research directions and outlines the contribution of our work to the existing body of knowledge, Section 3 presents architectures of the multimodal ocular biometrics, Section 4 describes experimental setup, Section 5 presents experimental results, and Sections 6 and 7 include the discussion and conclusion, respectively.

## 2. Related Work

### 2.1. Eye Movement-driven Biometrics

The human eye exhibits several basic types of eye movement in response to various stimuli (both internal and external). In the field of human-computer interaction, fixations and saccades are of primary interest. Fixations occur when the eye globe is held in a relatively stable position such that the fovea remains centered on an object of interest, providing heightened visual acuity. Saccades occur when the eye globe rotates quickly between points of fixation, with very little visual acuity maintained during rotation. The term scanpath refers to the spatial path formed by a sequence of fixations and saccades.

200 Kasprowski and Ober [4] employed the uncalibrated  
201 positional signal captured by a custom-made eye tracking  
202 in a verification scenario. The signal was processed by  
203 Naïve Bayes, C45 Decision Tree, SVM polynomial, and  
204 KNN (k=3, 7) algorithms. The visual stimulus was pre-  
205 sented as a sequence of jumping dots, and data was cap-  
206 tured for 8 sec at a frequency of 250 Hz. The best reported  
207 result provided HTER = 12% (FAR = 1.48%, FRR =  
208 22.59%), obtained from 9 subjects. Subsequently in [5], the  
209 authors extended their research by working with features  
210 such as average velocity direction, eye distance to stimulus,  
211 distance between eyes, and features extracted from discrete  
212 Fourier and wavelet transforms. The resulting feature  
213 vectors were merged by voting method for an average  
214 HTER of 3.88-11.25%; however, the authors did not report  
215 the number of subjects considered.

216 Bednarik et al. [6] employed such metrics as pupil di-  
217 ameter/dilation, eye velocity, and distance between eyes  
218 captured by a commercial Tobii ET-1750 eye tracking  
219 system in an identification scenario. Metrics were pro-  
220 cessed via Fourier spectrum, principal component analysis,  
221 and a combination of the two. The visual stimulus was a  
222 centrally positioned cross, displayed for a period of 1 sec,  
223 and data was captured for 12 subjects with a sampling  
224 frequency of 50 Hz. For each subject, data was captured  
225 during a single recording session, and the best reported  
226 result yielded an identification rate of 92%, obtained by  
227 weighted fusion of the three metrics.

228 Kinnunen et al. [6] employed information about the an-  
229 gles the eye travels within a temporal window, captured by  
230 a commercial Tobii X120 eye tracking system in a verifi-  
231 cation scenario. Captured information was processed into  
232 features by a Gaussian mixture model, enhanced by a uni-  
233 versal background model. The visual stimulus was a 25 min  
234 comedy video, and data was captured for 17 subjects with  
235 a sampling frequency of 120 Hz. Each subject viewed two  
236 videos, one of which was employed for enrollment and the  
237 other for verification. The best reported result yielded an  
238 HTER of 29.4%, obtained by weighted fusion.

239 Rigas et al. [7] investigated a method in which a se-  
240 quence of fixations and saccades was represented by a  
241 minimum spanning tree (MST). MST templates were  
242 compared by a statistical test designed to extract mean and  
243 variance. The visual stimulus was a set of facial images,  
244 with a total of 10 images presented during each recording  
245 session for 4 sec each. Each subject participated in 8 re-  
246 cording sessions over two days, and data was collected by a  
247 Dual Purkinje eye tracking system with a sampling rate of  
248 50 Hz. EER was reported at 30%.

249 Komogortsev et al. [8] proposed a method of authenti-  
cation via oculomotor plant characteristics (OPC) esti-  
mated from eye movements, with obtained OPC templates  
compared by Hotelling's T-square test. The visual stimulus  
was presented as a jumping dot with fixed amplitude, and  
eye movements were recorded for 59 subjects over two

250 recording sessions using an EyeLink 1000 eye tracking  
251 system with a sampling rate of 1000 Hz. The best reported  
252 result yielded an HTER of 19%.

253 Holland and Komogortsev [9] investigated individual  
254 and aggregated scanpath characteristics, representative of  
255 the brain's visual attention strategies during reading.  
256 Weighted mean fusion was employed to combine scores  
257 obtained by various characteristics. Eye movements were  
258 recorded for 32 subjects over four recording sessions using  
259 an EyeLink 1000 eye tracking system with a sampling rate  
260 of 1000 Hz. The best reported result yielded EER of 27%.

261 Komogortsev et al. [10] proposed to combine OPC and  
262 CEM modalities for the same reading stimulus and re-  
263 cording environment. When considered separately, OPC  
264 and CEM achieved HTER of approximately 27%; however,  
265 weighted fusion of the two provided an HTER of 19%,  
266 indicating a 30% improvement in accuracy.

267 Several areas that must be improved in eye movement  
268 related biometrics include: 1) size of available biometric  
269 databases; 2) cost of equipment; and, 3) biometric accu-  
270 racy. The current work improves the state-of-the-art in these  
271 areas by: recording eye movements across 87 subjects,  
272 generating the largest available database for eye move-  
273 ment-based biometrics; the use of a single, low-cost image  
274 sensor, costing approximately \$20 in comparison to the  
275 commercial systems employed in previous research, which  
276 may cost \$5000-35000; and a resulting HTER of 33.6%  
277 provided by the combined eye movement-driven traits, an  
278 accuracy on par with previous findings.

## 2.2. Iris

### 2.2.1 Iris Biometrics on Low Cost Equipment

280 Lu et al. [11] modified a Sony Erickson P800 phone by  
281 adding an eye cap with custom-made lens and an IR light.  
282 The system was designed to capture grayscale iris images at  
283 the resolution of 640×480. The authors implemented  
284 Daugman's algorithm [12] on their mobile platform, and  
285 evaluation of the mobile algorithm with the CASIA-IrisV1  
286 database was performed. FAR of 0.13-4.3% and FAR 0-8%  
287 was obtained, though the authors did not provide perfor-  
288 mance results using iris images captured by with the con-  
289 structed device.

290 Thomas et al. [13] employed an Airlink SkyIPCam500W  
291 to capture 640×480 images in near infrared spectrum. The  
292 camera captured several images at the rate of 30 Hz. An LG  
293 IrisAccess system was employed for actual iris matching,  
294 and a small database of six subjects was used. The system  
295 was able to identify all users correctly and one additional  
296 person was correctly rejected as an imposter.

297 Sirohey et al. [14] located eye corners, eyelids, and irises  
298 in video data in order to determine changes in gaze direc-  
299 tion and blinking, respectively. Considering the iris is al-  
ways darker than the sclera, they started with segmentation  
of the scleric iris boundary. Then, anthropometric measures

bounded on the size of the iris relative to the size of the eye, and iris movements have limits imposed on them by the size of the eye. For eyelid edge, they used information about the eye corners and the iris center. The upper eyelid edge forms an arc that bounds the eye above the iris center. A flow-based method describes the movement of each component of the periocular region between frames, with respect to head motion, estimated by a flesh-tone color segmentation that gives a blob corresponding to the head.

Kai and Du [15] used a video sequence from the IUPUI data set and proposed an iris recognition strategy from low-level quality data. The iris is segmented by direct least square fitting, and a gradient-based strategy is applied locally to the segmented area to detect noise within the iris ring. Then, they proposed a two stage classification strategy, using information from different scales analyzed by SURF keypoint detection and Gabor filter decomposition.

Aiming to perform biometric iris recognition on low-quality video data, Jilela and Ross [16] fused information at the data-level in two stages: application of a so-called Principal Components Transform (PCT) to individual frames and averaging of the resulting images. The performance of image-level fusion was compared against that of score-level fusion, having authors observe significant improvements of the proposed technique, when compared to the use of any individual frame. Similarly, Hollingsworth et al. [17] took advantage of the temporal continuity in videos to improve matching performance using signal-level fusion. From multiple frames of a frontal iris video, they created a single average image, having observed that signal-level fusion performs comparably to state-of-the-art score-level fusion techniques, with less computation burden.

In summary, the iris capture setup employed in the current work is similar to existing studies; however, to the best of our knowledge, there is no research that combines iris and eye movement-driven biometric modalities. This work fills that gap by using a single image sensor to infer information about the iris and eye movements for biometric purposes.

### 2.2.2 Counterfeit Resistance

Recent studies report that existing iris-based biometric systems can be spoofed by simple replicas such as printed pictures of the iris [18]. There are also studies that propose quite sophisticated mechanisms for spoofing, e.g., semi-transparent contact lens [3]. As a result, there is a substantial body of work that describes aliveness and spoofing detection methods, e.g., [19, 20]; however, the race between ideas for iris spoofing and prevention methods primarily takes the route of manufacturing better material to represent the iris, and methods that detect non-human artifacts in that material [19].

We hypothesize that eye movement-related biometric methods that are driven by the sophisticated structure of the oculomotor plant and brain would be extremely effective in

rejecting intruders with iris replicas of even the highest possible quality. In that case, the accuracy of the underlying eye movement-driven method would determine the accuracy of fake iris rejection. The OPC and CEM methods discussed in this work can serve as a backbone for such counterfeit resistance mechanisms.

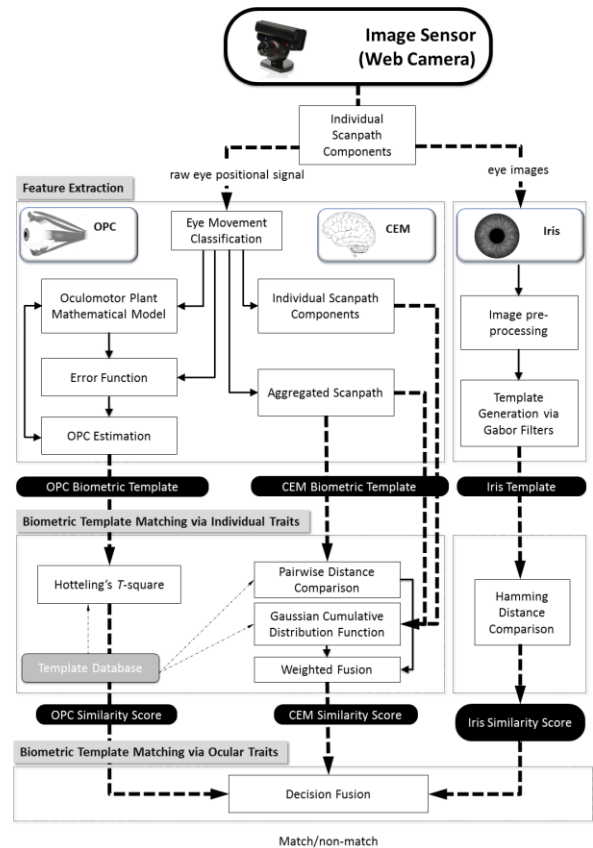


Figure 1: Multimodal ocular biometrics.

### 3. Multimodal Ocular Biometrics Approach

Three components comprise the multimodal ocular biometrics approach: 1) the internal, non-visible, anatomical structure of the human eye, represented by Oculomotor Plant Characteristics (OPC); 2) the visual attention strategies employed by the brain, represented by Complex Eye movement patterns (CEM); and, 3) the unique physical structure of the iris. All three traits may be derived from the same image stream, captured by a single camera sensor and driven by eye tracking software. Eye tracking software estimates the eye positional signal from the sequence of eye images, supplies this data to the OPC and CEM modules, and forwards images of the eye to the iris-processing module for subsequent generation of iris templates. Each module is capable of producing a comparison score that is fused into a single score for the final acceptance/rejection decision. In the current implementation, scores are fused by



400 a simple weighted sum approach. Figure 1 depicts an  
401 overview of the proposed approach and the mechanics of  
402 each module.

### 403 3.1. Oculomotor Plant Characteristics (OPC) 404

405 The anatomy of the human eye provides a unique op-  
406 portunity for biometric authentication, as there are a mul-  
407 titude of anatomical components that comprise the oculo-  
408 motor plant (OP). These components include: the eye  
409 globe; the surrounding tissue and ligaments; six extraocular  
410 muscles (EOMs), each containing thin and thick filaments;  
411 tendon-like components; and various tissues and liquids  
412 [21]. The static and dynamic properties of the OP are rep-  
413 resented by: the eye globe's inertia; the force-velocity  
414 relationship of individual muscles; the resistive properties  
415 of the eye globe, muscles, and ligaments; the characteristics  
416 of the neuronal control signal, sent from the brain to the  
417 EOMs; and the speed of propagation of the neuronal control  
418 signal. Individual properties of the EOMs vary de-  
419 pending on their roles, which are two: agonist, representing  
420 the contracting muscle which pulls the eye globe; and an-  
421 tagonist, representing the lengthening muscle resisting the  
422 pull [22].

423 In this work, we employ a biometric method proposed by  
424 Komogortsev et al. [8]. In this method, a mathematical  
425 model of the eye simulated saccades and compares them to  
426 the recorded saccades extracted from the raw positional  
427 signal. Computed differences trigger OPC estimation pro-  
428 cedures which attempt to find OPC values which minimize  
429 the difference in positional signal. Optimized OPC values  
430 form the biometric template.

431 Similar to the original method, we have selected the  
432 following nine OPC to form entries in the biometric tem-  
433 plate: length tension, series elasticity, passive viscosity of  
434 the eye globe, agonist force-velocity relationship, antago-  
435 nist force-velocity relationship, tension intercept, and ago-  
436 nist and antagonist tension slopes [8]. The resulting tem-  
437 plate can be compared by Hotelling's T-square test to an-  
438 other template, returning a probability score that can be  
439 employed to determine similarity.

### 440 3.2. Complex Eye Movement Patterns (CEM) 441

442 Complex Eye Movement patterns (CEM) represent the  
443 cognitive strategies employed by the brain throughout the  
444 guidance of visual attention. The human eye is connected to  
445 and controlled by a complex network of brain regions,  
446 sub-regions, and neural pathways [22, 23]. Information is  
447 transmitted from region to region along neural pathways in  
448 the form of neural signals, which may convey visual field  
449 information from the eye or control information from the  
450 brain. The firing rate of individual neural signals (which  
451 occur in sustained bursts) is dependent on the physical  
452 properties of the involved neurons and surrounding brain

450 tissue. As well, this neural activity is influenced by the task  
451 being performed, which may cause variation in baseline  
452 firing rates, firing rate profiles, and modulations of neu-  
453 ronal activity related to particular stimuli and behavioral  
454 responses [24].

455 We define fixation-based metrics as those metrics, which  
456 depend solely upon fixations and the mechanics involved in  
457 generating fixations. Fixation-based metrics include: fixa-  
458 tion count ( $f_1$ ) and average fixation duration ( $f_2$ ). Fixa-  
459 tion-based metrics involve and are dependent upon the:  
460 dorsal layers and rostral pole of the superior colliculus,  
461 nucleus raphe interpositus in the midline of the pons, pos-  
462 terior parietal cortex, and visual cortex areas V1-V5 [22,  
463 23].

464 We define saccade-based metrics as those metrics, which  
465 depend solely upon saccades and the mechanics involved in  
466 generating saccades. Saccade-based metrics include: av-  
467 erage vectorial saccade amplitude ( $f_3$ ), average horizontal  
468 saccade amplitude ( $f_4$ ), average vertical saccade amplitude  
469 ( $f_5$ ), average vectorial saccade velocity ( $f_6$ ), average vecto-  
470 rial saccade peak velocity ( $f_7$ ), slope of the ampli-  
471 tude-duration relationship ( $f_8$ ), slope of the main sequence  
472 relationship ( $f_9$ ), and velocity waveform indicator ( $f_{10}$ ).  
473 Saccade-based metrics involve and are dependent upon the:  
474 ventral layers of the superior colliculus, paramedian pon-  
475 tine reticular formation, rostral interstitial nucleus of the  
476 medial longitudinal fasciculus, frontal eye fields, and lat-  
477 eral intra parietal [22, 23].

478 We define scanpath-based metrics as those metrics  
479 which are derived from the size, shape, or pattern of the  
480 overall eye movement scanpath, and are often related to the  
481 visual search strategy employed in extracting information  
482 from a given stimuli. Scanpath-based metrics include:  
483 scanpath length ( $f_{11}$ ), scanpath convex hull area ( $f_{12}$ ), re-  
484 gions of interest ( $f_{13}$ ), inflection count ( $f_{14}$ ), and spatial  
485 distribution represented by a pairwise distance comparison  
486 ( $f_{15}$ ). Scanpath-based metrics involve and are dependent  
487 upon the brain regions involved in fixation- and sac-  
488 cade-based metrics, as well as the conscious and  
489 sub-conscious memory mechanisms responsible for the  
490 guidance of visual search [25, 26].

491 Fixation and saccade related information is processed by  
492 the Individual Scanpath Components module and aggreg-  
493 ated information is processed by the Aggregated Scanpath  
494 module. Components are combined by a weighted fusion  
495 method which outputs a single similarity score for a given  
496 pair of CEM templates. Additional details are provided  
497 elsewhere [9].

### 498 3.3. Iris 499

500 Considering the specific characteristics of iris data, it is  
501 especially important to define an initial region of interest,  
502 from which subsequent processing occurs. The near infra-  
503 red (NIR) structured light guarantees maximum contrast

500 between the pupil and any remaining data. Hence, the first  
501 step comprises the detection of a bounding box that con-  
502 tains the pupil, made according to orthogonal projections.  
503 Then, a first order gradient-based edge detection [27] feeds  
504 a circular Hough transform phase, yielding the parameter-  
505 ized papillary boundary. Morphological constraints are  
506 especially useful to constrain the potential regions of search  
507 for the scleric boundary, accomplished in a similar way to  
508 the inner boundary. The translation into the Polar domain  
509 gives rough invariance to changes in scale. An optimal  
510 Gabor filter [12] configuration (wavelength:  $1/4$ , orientation  
511  $5\pi/8$ , phase offset: 0, sigma Gaussian:  $1/8$ , spatial aspect  
512 ratio: 1) is selected to extract the iris biometric template<sup>1</sup>.  
513 Template matching is performed in angularly constrained  
514 regions of the normalized data, where eyelid and eyelash  
515 occlusions are less probable. As a result of template  
516 matching, a distance score is returned by the iris module.  
517 The score can be employed in the similarity decision. It  
518 should be stressed that more elaborate segmenta-  
519 tion/encoding strategies were not considered, due to the  
520 limited resolution of obtained iris data.

## 4. Experimental Setup

### 4.1. Equipment & Software

521 Eye movement recording and iris capture were simul-  
522 taneously conducted using a PlayStation Eye web camera  
523 (approximate cost of \$20). The camera recorded at the  
524 resolution of 640×480 pixels with a frame rate of 75 Hz.  
525 The existing IR filter was removed and a piece of unex-  
526 posed film was inserted as a filter for the visible spectrum  
527 of light. A Clover Electronics IR010 Infrared Illuminator  
528 (approximate cost of \$33) and two IR diodes (approximate  
529 cost of \$2) placed on the body of the camera were em-  
530 ployed to improve the quality of iris illumination and eye  
531 tracking accuracy. The web camera and main IR array were  
532 each installed on the flexible arm of a Mainstays Halogen  
533 Desk Lamp (total approximate cost \$20) to provide an  
534 installation that can be adjusted to specific users. A chin  
535 rest (readily available from a commercial eye tracking  
536 system) was employed for head stabilization to improve the  
537 quality of acquired data. In a low-cost scenario, a com-  
538 fortible chinrest can be constructed from very inexpensive  
539 materials.

540 The stimulus was displayed on a 19-inch LCD monitor  
541 with a refresh rate of 60 Hz. The distance between the eye  
542 and the screen was approximately 540 mm.

543 ITU Gaze Tracker [28], publicly available eye tracking  
544 software, was employed for eye tracking purposes. The  
545 software was modified to present the required stimuli and  
546 store an eye image every three seconds, in addition to the  
547

548 <sup>1</sup> Optimal parameters were selected based on analysis of the  
549 training dataset.

550 existing eye tracking capabilities. Eye tracking was done in  
551 no-glint mode. Duchowski provides an overview of general  
552 eye tracking principles [23].

### 4.2. Stimulus

553 A complex pattern stimulus was constructed that em-  
554 ployed the Rorschach inkblots commonly used in psycho-  
555 logical examination [29], in order to provide relatively  
556 clean patterns which were likely to evoke varied thoughts  
557 and emotions in participants. Inkblot images were selected  
558 from the original Rorschach psychodiagnostic plates and  
559 sized/cropped to fill the screen. Participants were instructed  
560 to examine the images carefully, and recordings were per-  
561 formed over two sessions, with 3 rotations of 5 inkblots per  
562 session. Each inkblot was displayed for 12 sec, for a total of  
563 3 min per session.

### 4.3. Participants & Data Collection

564 Eye movement and iris data was collected for a total of  
565 87 subjects (60 male, 27 female), ages 18 – 47 with an  
566 average age of 22.6 (SD = 4.8). An Institutional Review  
567 Board approved data collection procedures, and all subjects  
568 provided informed consent. Each subject participated in  
569 two recording sessions with an interval of approximately 15  
570 min between sessions.

571 During the data collection phase, the recording facilita-  
572 tors were instructed to adjust the equipment to provide high  
573 quality eye movement data and iris images. The quality of  
574 the eye movement data was controlled by the magnitude of  
575 calibration error. The facilitators were instructed to adjust  
576 the equipment to keep this error under 2° of the visual angle  
577 for any participant. The quality of iris images was con-  
578 trolled by visual inspection that targeted iris diameter in a  
579 range of 100 pixels, was in focus, with iris pattern clearly  
580 visible. In cases where maintaining high quality eye  
581 movement data and iris images at the same time was not  
582 possible, the preference in quality was given to the eye  
583 movement data. This scenario happened for several sub-  
584 jects, for whom high quality iris images degraded the per-  
585 formance of the eye tracking software. Figure 2 provides an  
586 example eye movement scanpath collected from a single  
587 subject/inkblot, and Figure 3 provides examples of col-  
588 lected iris quality.

### 4.4. Datasets & Data Quality

590 Across all eye movement recordings, mean positional  
591 accuracy represented by the magnitude of calibration error  
592 was 1.06° (SD = 0.64°). For each recording session, one  
593 best iris image was selected manually to provide a  
594 one-to-one correspondence between related OPC, CEM,  
595 and iris templates. Captured iris images had mean diameter  
596 of 103.3 pixels (SD = 22 pixels). Mean focus score com-  
597 puted by eq. 15 in [30] was 75 (SD = 24.7). For compari-  
598

son, the ICE 2005 iris dataset [31] has mean focus score of 163 (SD = 27.5).

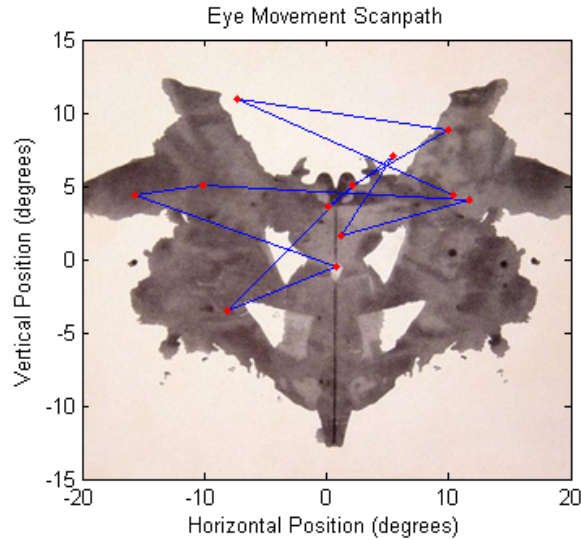


Figure 2: Example scanpath.

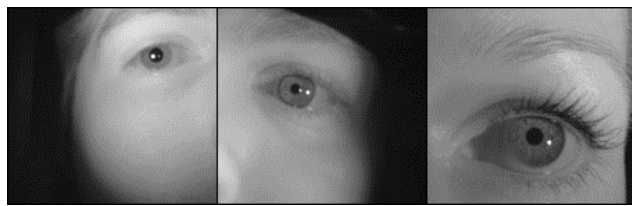


Figure 3: Example iris quality. Left image: poor quality. Middle image: acceptable quality. Right image: good quality.

## 5. Results

Results are presented in Figure 4 and Table 1.

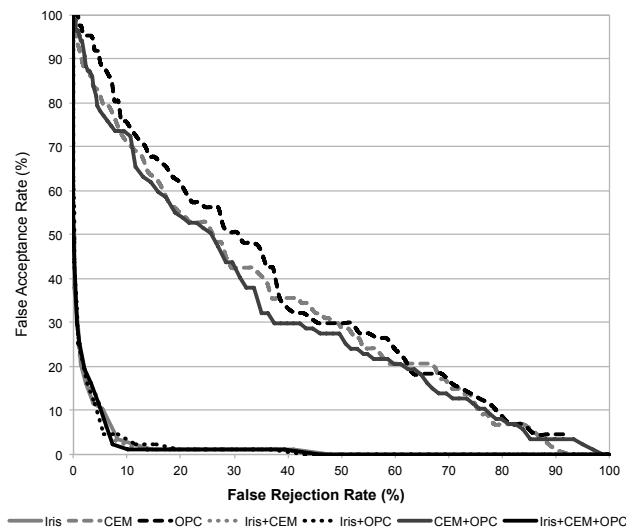


Figure 4: Detection error tradeoff. “+” sign indicates weighted fusion with weights presented in Table 1.

Table 1. Decidability index and HTER for each method. Decidability index is computed by eq. 14 in [30]. HTER computed as  $(FAR+FRR)/2$  is derived from the data points that are as close as possible to the interpolated EER. OPC\_h and OPC\_v represent the scores obtained from the horizontal and vertical movement components respectively. Features related to CEM were identified in Section 3.1.

Method Name	Decidability Index	HTER
OPC h	0.35	41.7
OPC_v	0.39	40.5
OPC = $0.53*OPC\_h+0.47*OPC\_v$	0.5	37.1
CEM = $0.009*f_4+0.037*f_5+0.917*f_7+$ $+f_{11}*0.037$	0.58	36.3
Iris	3.07	5.9
$0.98*Iris+0.02*OPC$	3.09	5.1
$0.98*Iris+0.02*CEM$	3.08	5.7
$0.37*OPC+0.63*CEM$	0.68	33.6
$0.02*OPC+0.02*CEM+0.96*Iris$	3.1	4.8

### 5.1. Oculomotor Plant Characteristics (OPC)

HTER provided by OPC alone was 37.1%, much higher than the comparable result of 22.5% reported in [8]. The 65% increase in error is not unexpected considering a significant reduction in sampling frequency (75 Hz vs. 1000 Hz). We hypothesize that equipment precision (the minimum distance the eye should move before a shift in position is detected) is much lower on the web camera based eye tracker, which contributes to the increase in error. Consider the web camera eye tracker is approximately three orders of magnitude less expensive than commercial equipment, it is important to notice that OPC performance is still far from the random baseline.

### 5.2. Complex Eye Movement Patterns (CEM)

HTER provided by CEM alone was 36.3%, which is higher than the comparable result of 27% reported in [9]. We hypothesize this 34.4% increase in error is due to reduction in sampling rate and equipment precision. It is possible to notice that the increase in CEM error is much smaller than the increase in OPC error. There are two points to consider: 1) accurate estimation of the OPC may require a low-noise, accurate signal and high sampling rate; 2) initial error of 27% reported for CEM in [9] is higher than the error of 22.5% reported for OPC in [8]. Therefore, it is possible to make the preliminary conclusion that OPC provides better verification than CEM on higher accuracy



and sampling rate equipment; however, CEM is more tolerant to accuracy and sampling rate degradation than OPC.

### 5.3. Iris

Considering the demands given by ISO/IEC 19794-6 (“an iris diameter of more than 200 pixels is considered to be good”), the average dimension of the iris rings in the acquired are far below that value. Unavoidably, this gap in the amount of information should correspond to an increase in the observed error rates of the iris recognition model. Not surprisingly, we observed that the optimal Gabor configuration was obtained at shorter wavelengths than those obtained for more usual datasets of iris recognition experiments (e.g. the ICE dataset), yielding HTER values around 5.9%. These allowed us to conclude that even in such challenging data, iris rings contain discriminating information, with potential to be used for biometric recognition purposes. Additionally, we empirically observed that slight increases in the amount of information acquired correspond to substantial improvements in iris recognition performance.

### 5.4. OPC + CEM

Combining OPC and CEM increased the accuracy of the verification, yielding an HTER of 33.6%. This constitutes a 9.4% reduction in error compared to OPC and a 7.4% reduction in error compared to CEM. The magnitude of error reduction is smaller than the 30% reported by Komogortsev et al. [10]; however, it is still substantial.

### 5.5. OPC + CEM + Iris

Fusion of OPC and iris traits reduced error by 13.4% when compared to iris modality alone, and fusion of CEM and iris traits reduced error by 3.4% when compared to iris modality alone. The combination of OPC, CEM, and iris traits provided an error reduction of 19% when compared to the iris modality alone. This reduction in error is quite substantial, indicating high potential for the combined ocular biometrics approach on low-cost equipment.

## 6. Discussion

### 6.1. Counterfeit Resistance

The best HTER achieved by CEM and OPC modalities is 33.6%, quite high when compared to the 0% error rate for the detection of contact lens reported by He et al. [32]. Eye movement biometrics still has a long way to go in terms of accuracy; however, we hypothesize that in a race between the artifact and detection mechanisms, eye movement driven methods may provide more robust solutions in the long run.

### 6.2. Limitations

There are several limitations in this study. First, subjects did not move their heads during recording, which is unrealistic during normal computer use. Second, weights for the weighted fusion and thresholding were selected for the dataset as a whole, similar to [8-10]. Third, eye images for iris recognition were selected manually; however, it is not difficult to imagine automated mechanisms that would perform such selection automatically (e.g. [33]). Fourth, only a single eye image per recording was selected for iris recognition purposes. Possible employment of a larger range of images, similar to [16], may improve iris related accuracy. Fifth, both recording sessions were done in close temporal proximity, therefore negating possible impacts related to fatigue, illness, or drug consumption. The impact of these factors over a longer recording timeline should be investigated in future work.

## 7. Conclusion and Future Work

The current work proposed a multimodal ocular biometric approach that combines three physiological and behavioral traits related to Oculomotor Plant Characteristics (OPC), Complex Eye Movement patterns (CEM), and iris patterns. The results indicate that it is possible to extract biometric information encoded in those traits using a single image sensor. The image sensor employed in our study was an inexpensive web camera, which contrasts with previous eye movement-driven studies that employed high-quality, commercial eye tracking equipment. As a result, the largest existing database of eye movements and corresponding iris images of 87 people was recorded and will be publicly available.

From the eye movement-driven biometric perspective, our results support findings reported in previous research and indicate that OPC and CEM are able to provide some information about biometric identity even when using inexpensive image sensors.

From the iris biometrics perspective, we confirm that: 1) it is possible to achieve reasonably low error rates (HTER = 5.6%) when operating on data with resolution substantially lower than ISO/IEC 19794-6 recommendations; and 2) the discriminating information of the iris texture correlates weakly to eye movement-driven biometric sources, which makes it possible to strengthen biometric accuracy by combining information from these traits. As a result, when compared to iris authentication alone, the multimodal ocular biometric provided an error reduction of 19%, with a resulting HTER = 4.8%.

We hypothesize that eye movement-driven biometrics can serve as a complimentary method for aliveness and spoofing detection to already existing mechanisms in future biometric systems. We plan to address this issue in detail in our future work.

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