

# Real-Time Rendering

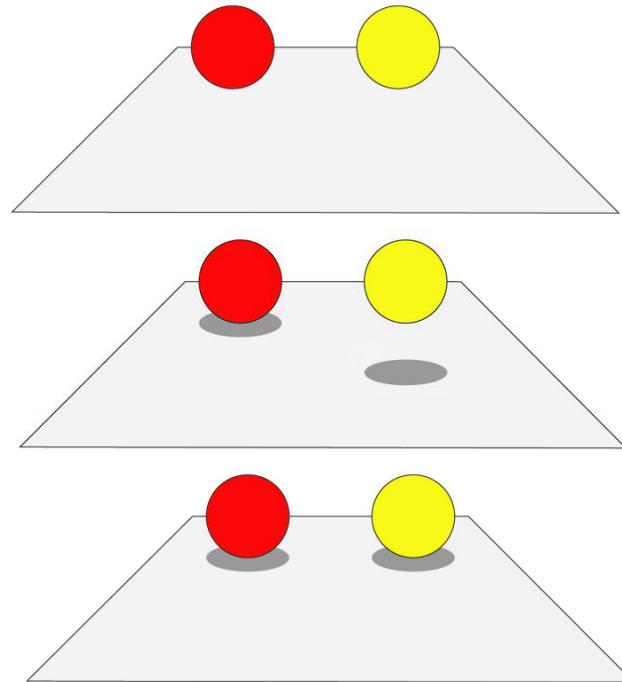
## *Intro to Shadows*



CSE 781  
Prof. Roger Crawfis



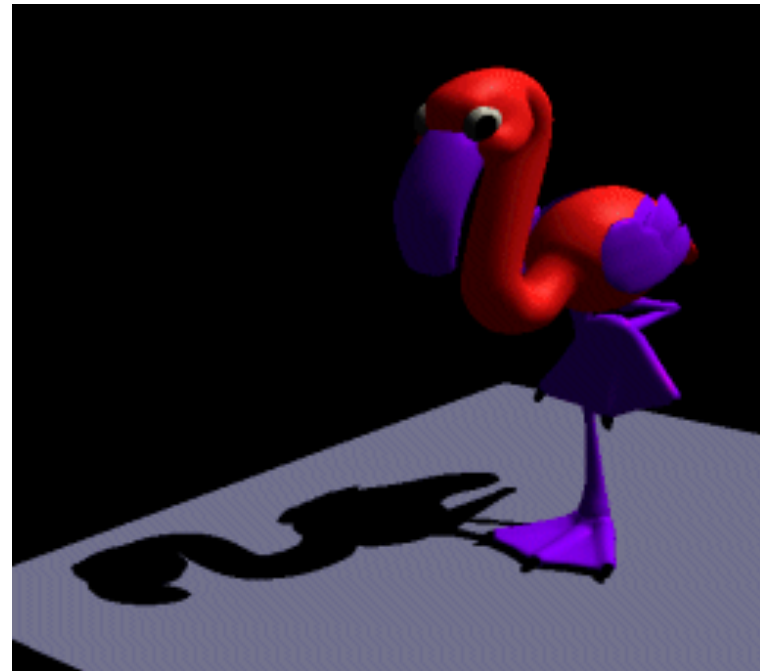
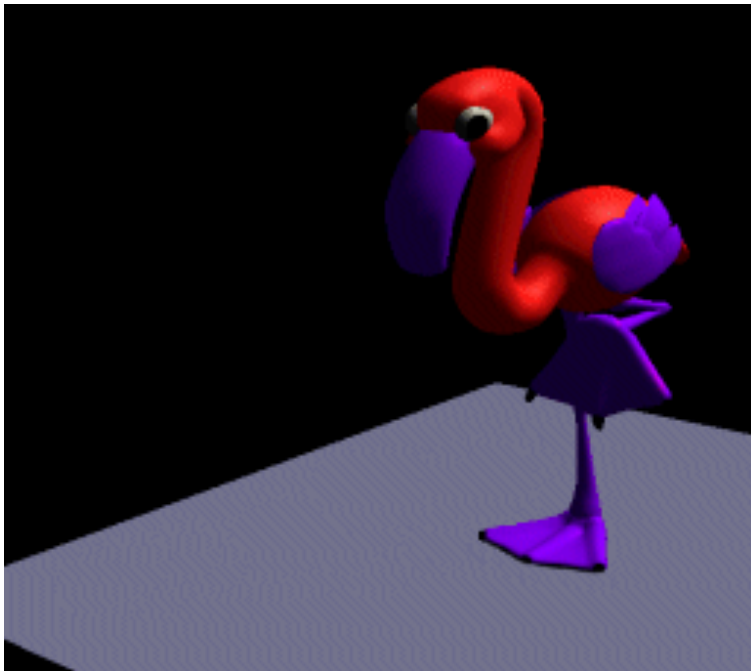
# Importance of Shadows



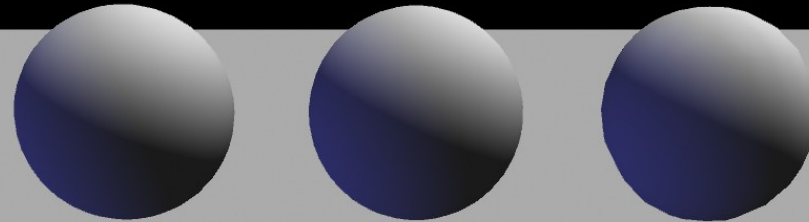
Trapezoid?

# Importance of Shadows

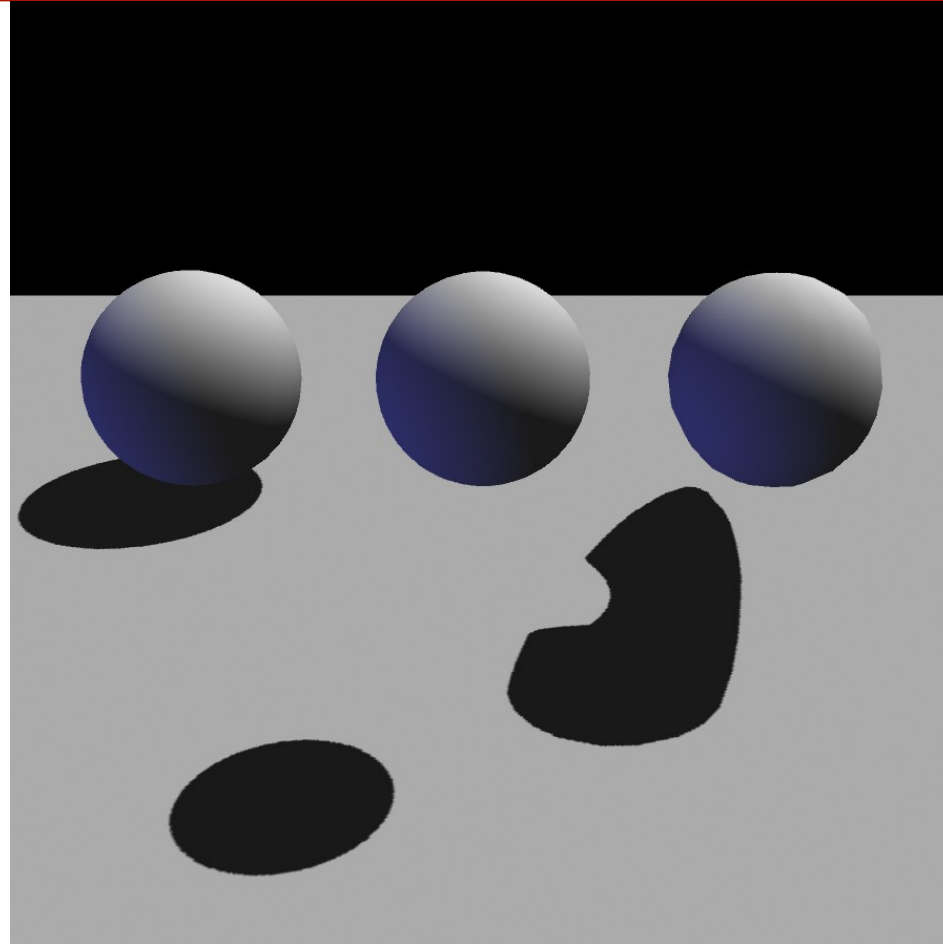
- Cue to object-object relationship.
- Provides additional depth cue.



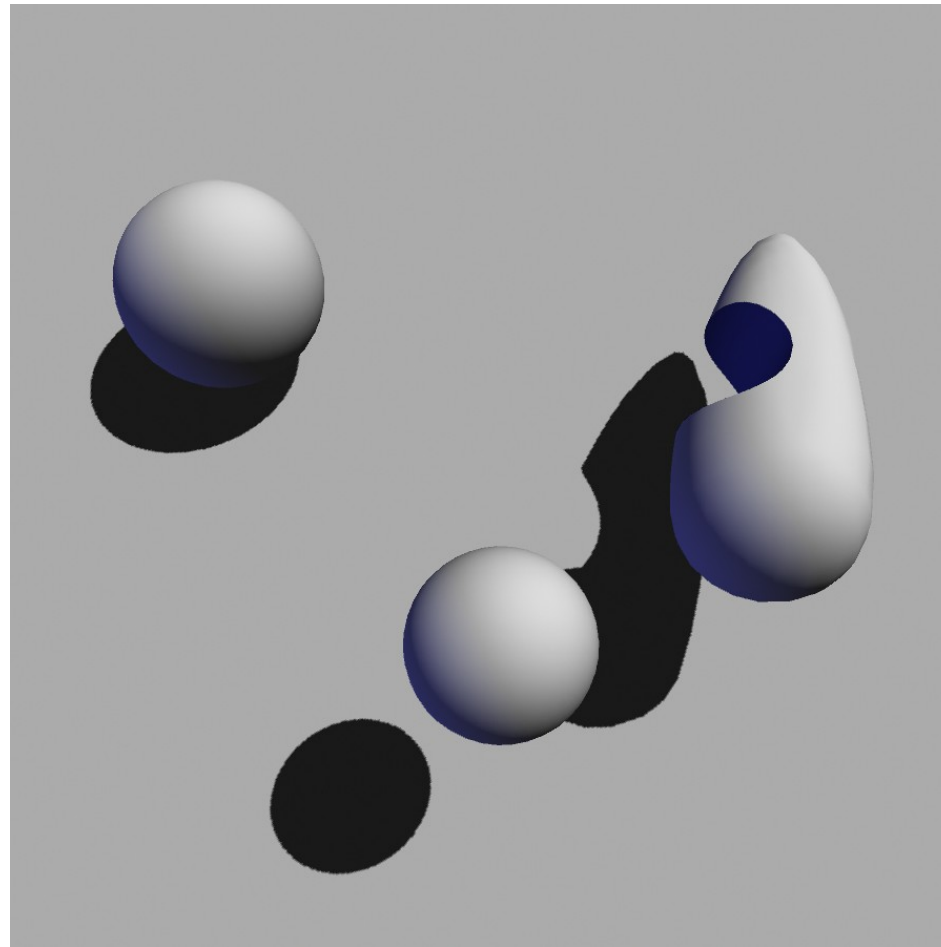
# Importance of Shadows



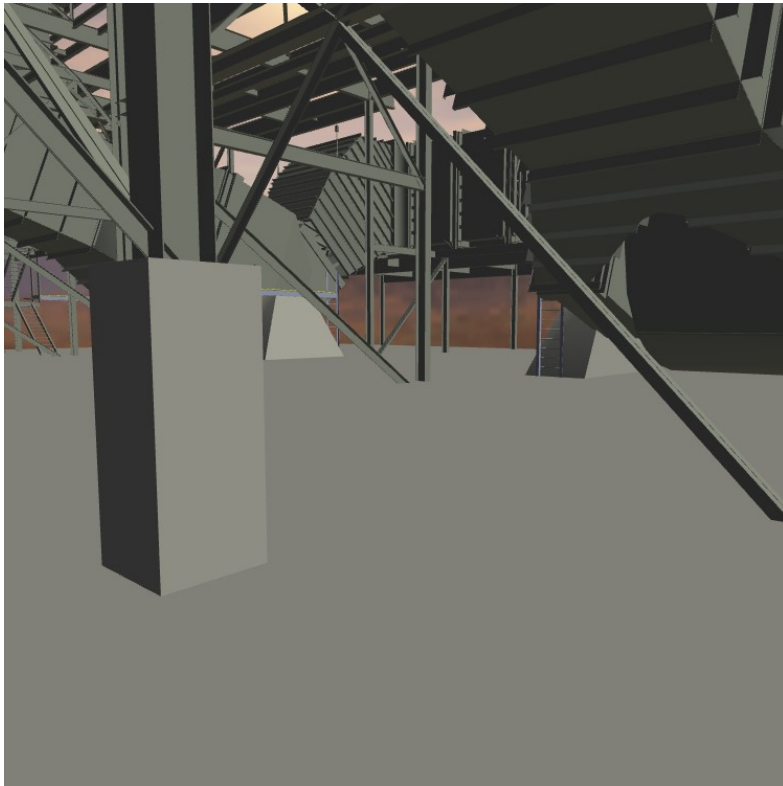
# Importance of Shadows



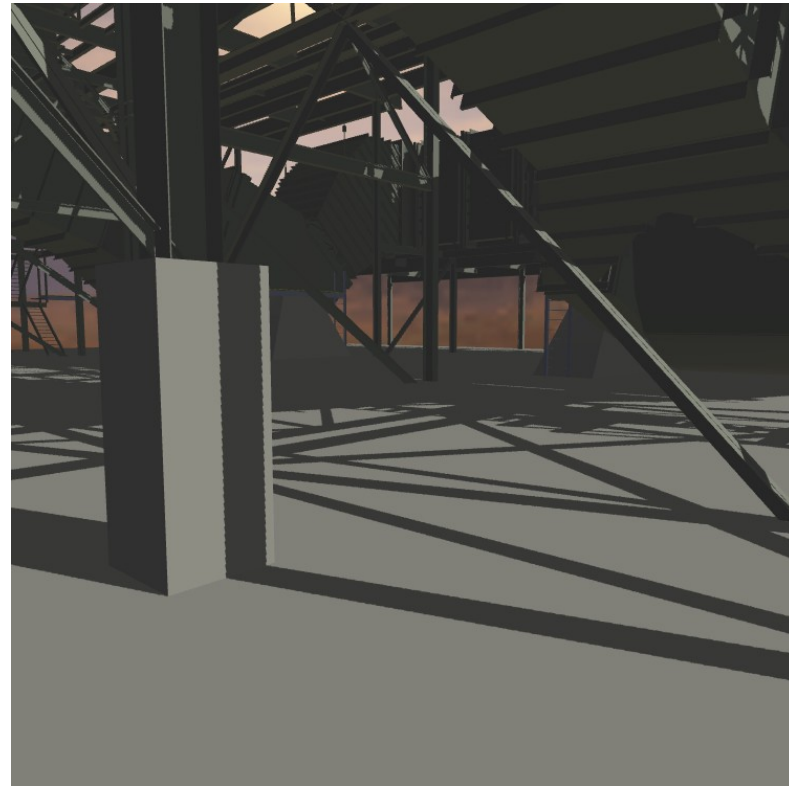
# Importance of Shadows



# Importance of Shadows



**Without shadows**



**With shadows**

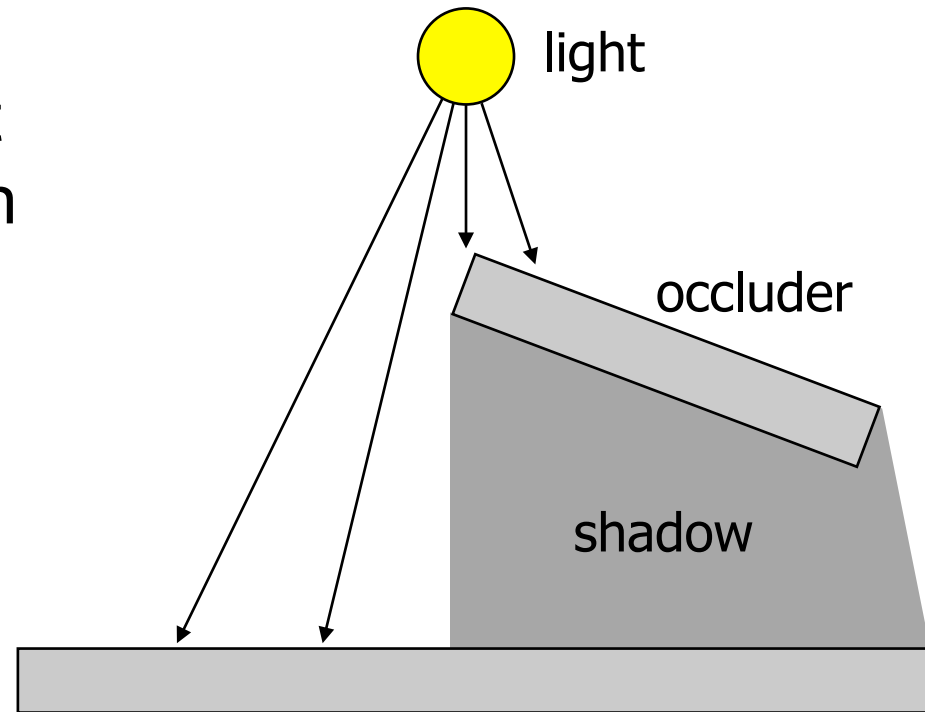
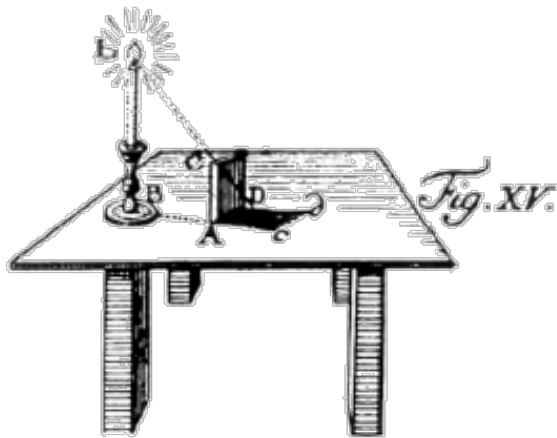


# Importance of Shadows

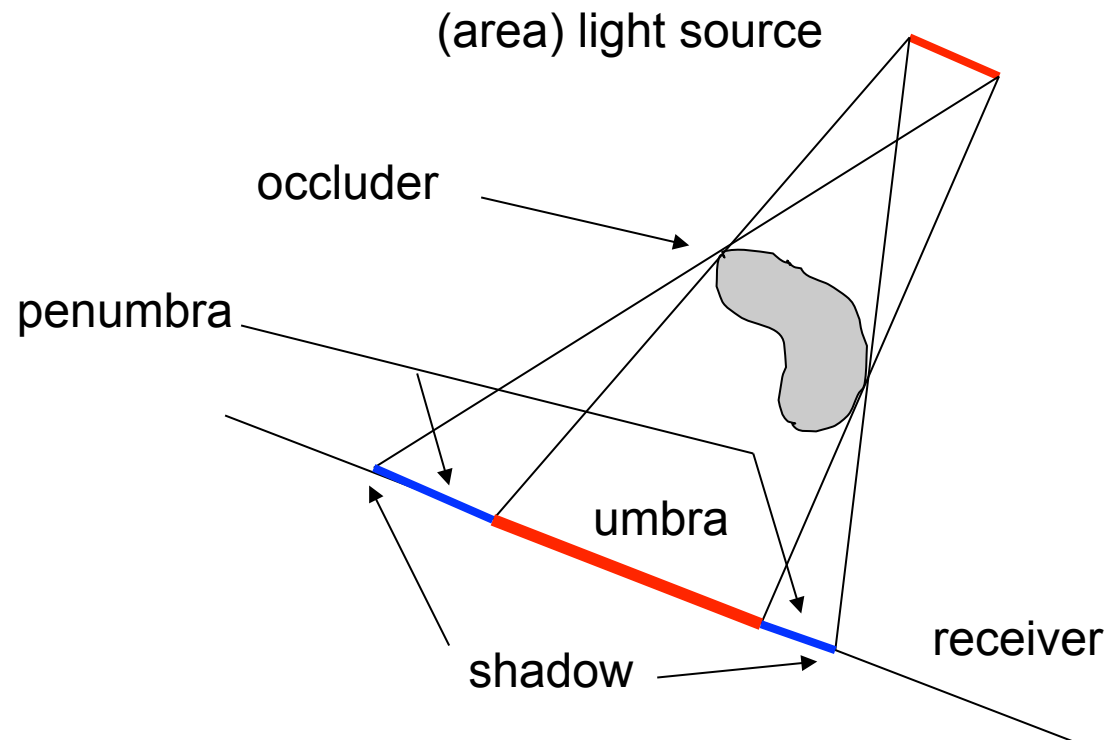


# Definition

**Shadow:** Darkness caused when part or all of the illumination from a light source is blocked by an occluder.

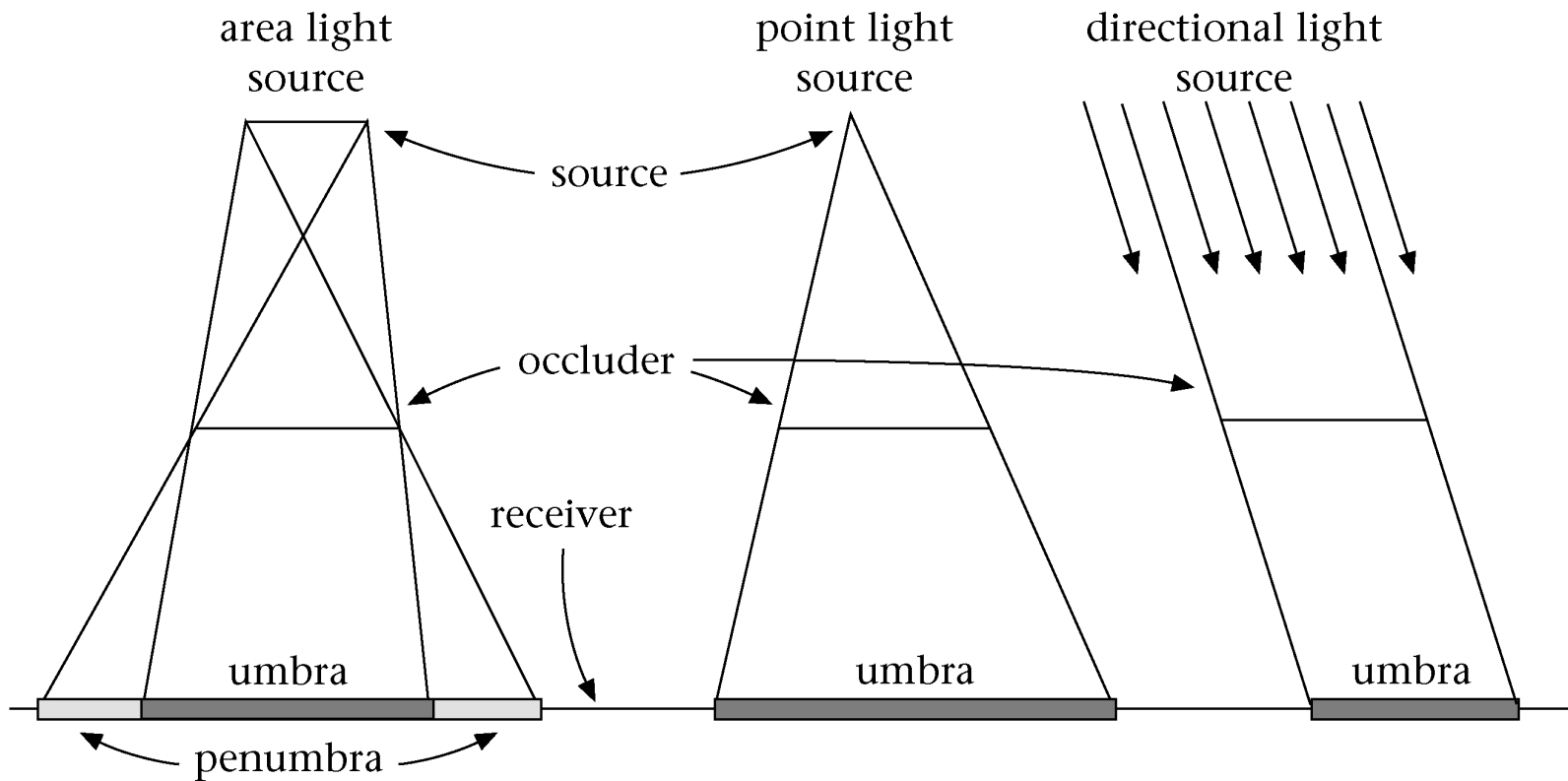


# Terminology



- **umbra** – fully shadowed region
- **penumbra** – partially shadowed region

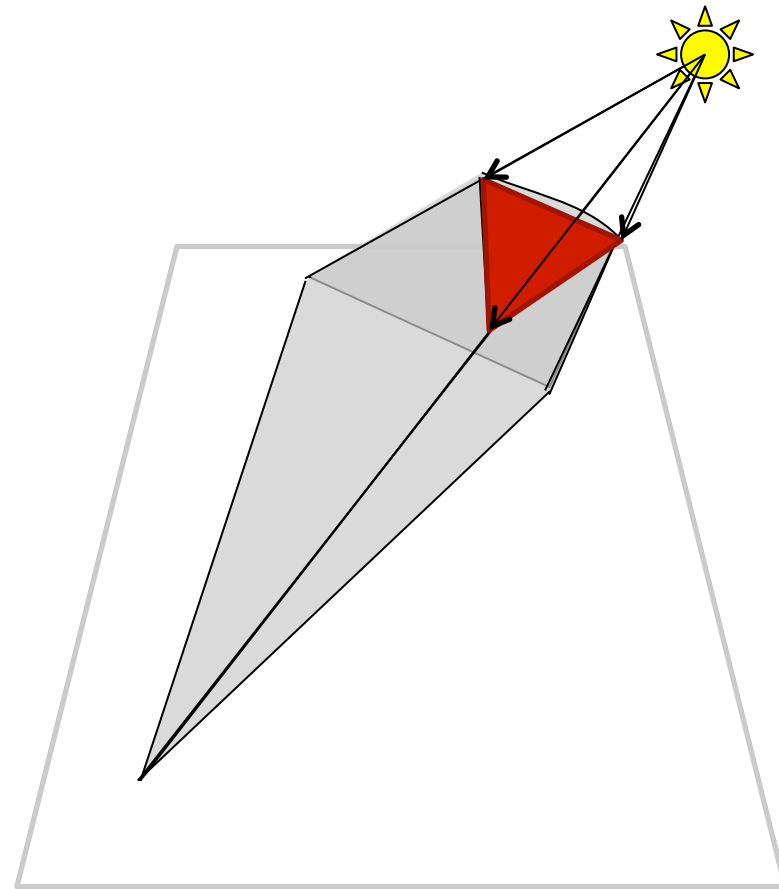
# Terminology



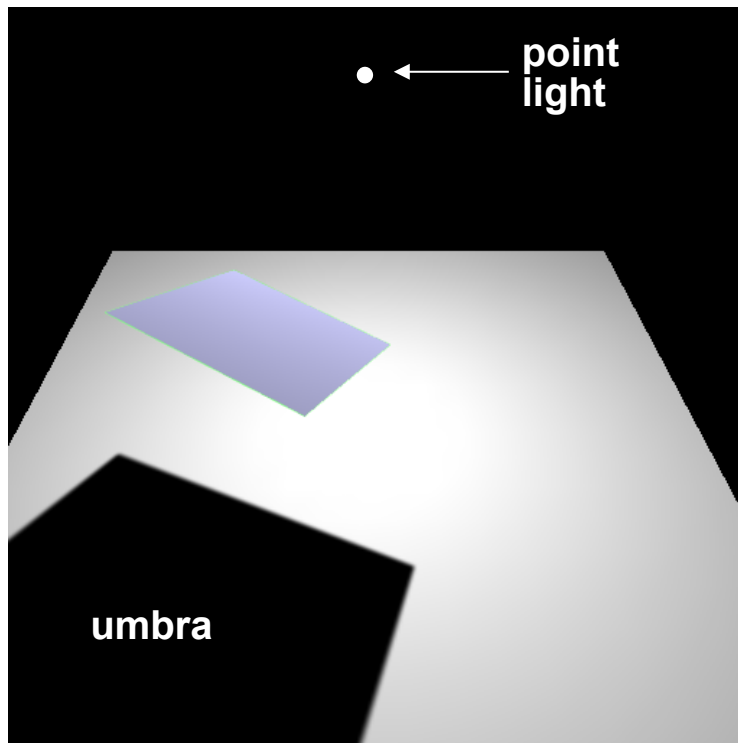
# Definition: Shadow Volume



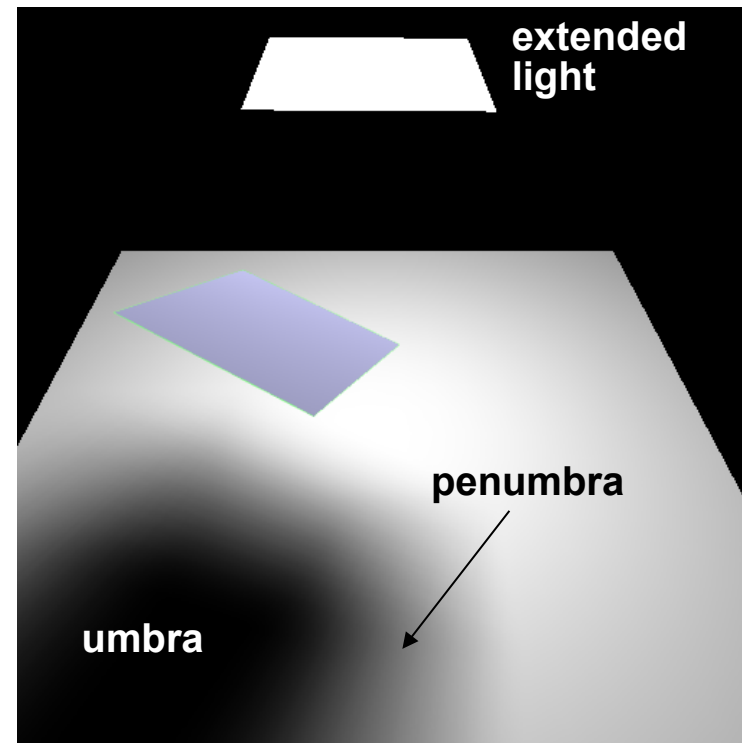
- Volume formed by extruding the occluder from the light source.
- Open and infinite
- Space inside the volume is in shadow.
- Space outside the volume is not.



# Hard and soft shadows



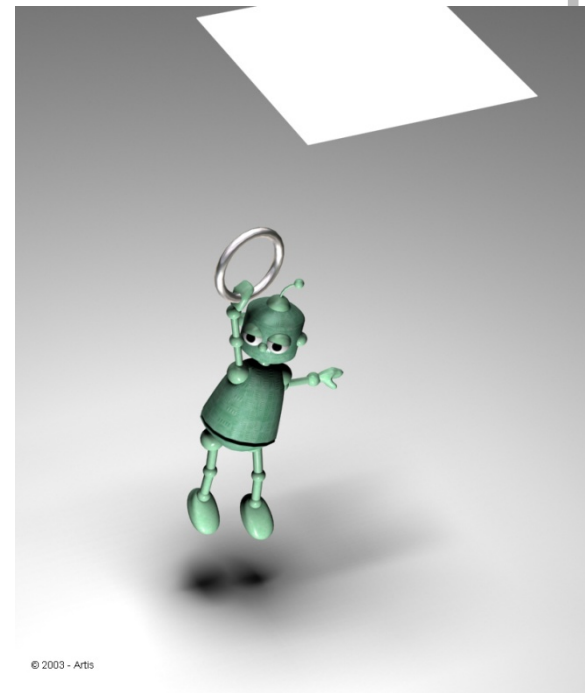
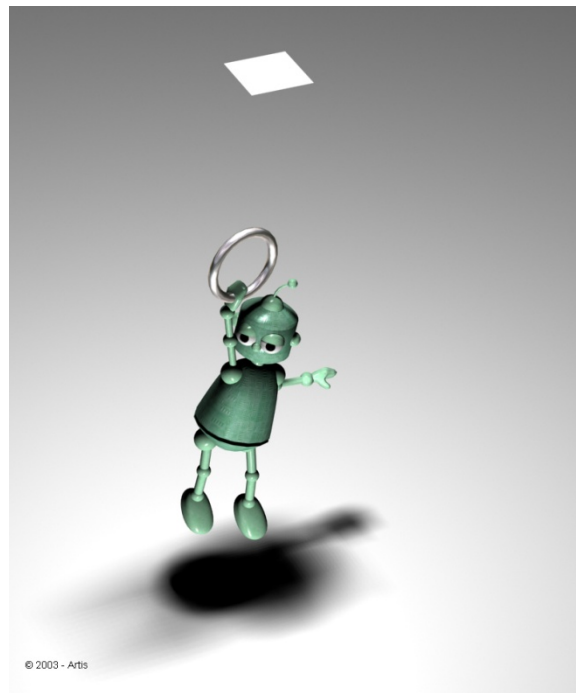
Hard shadow



Soft shadow

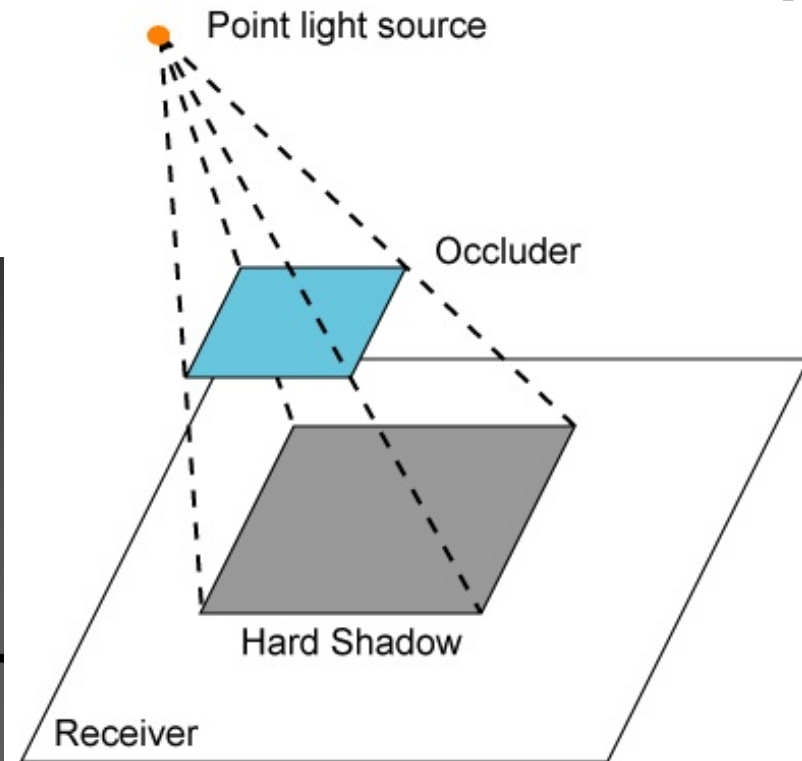
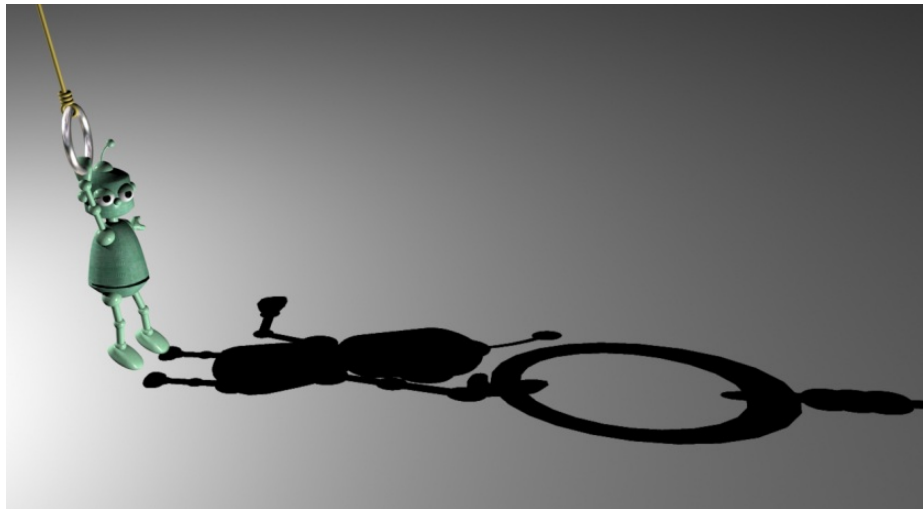
# Soft Shadows

- Shadow is a function of the area of the light source and the distance.



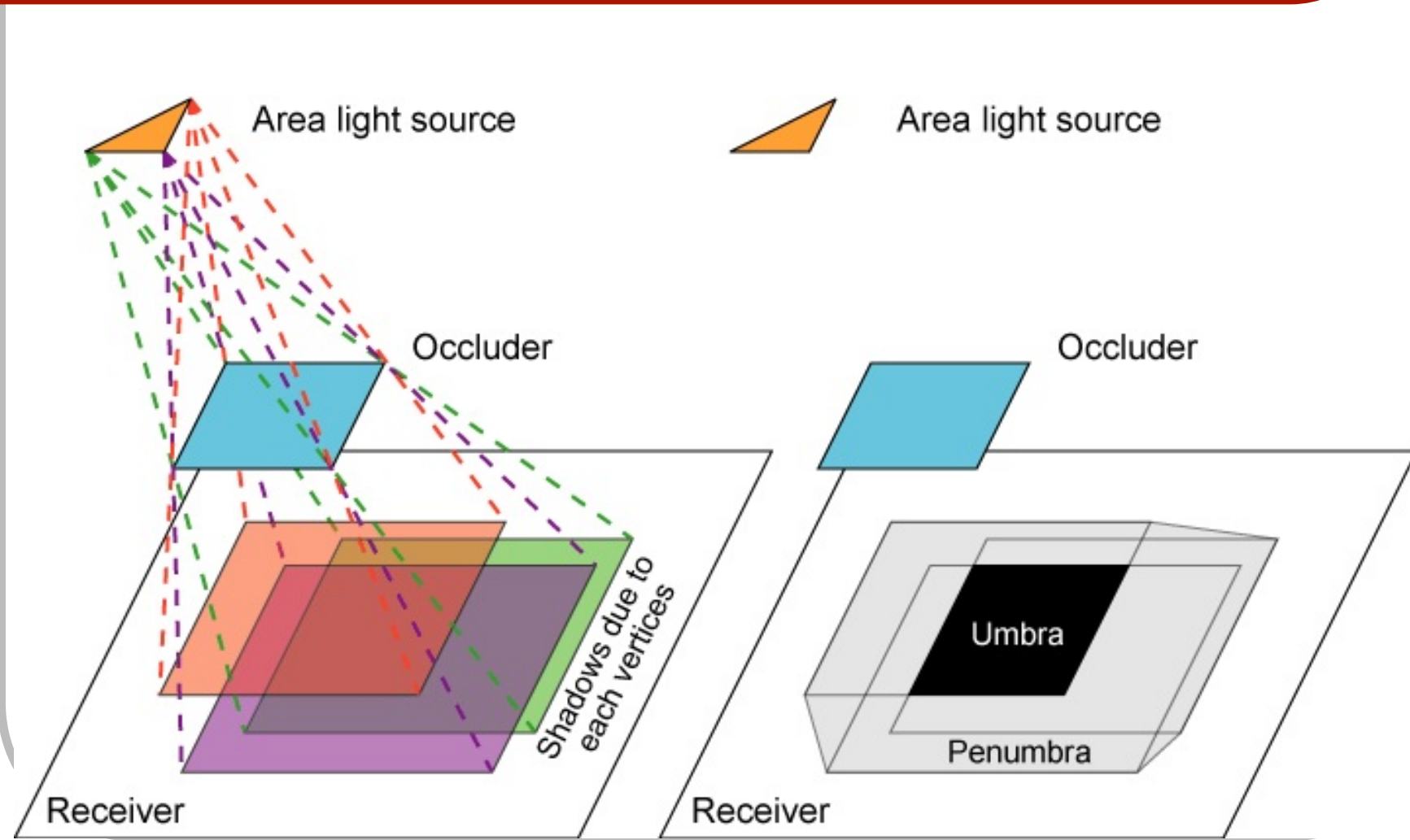
# Hard shadow creation

- For every pixel, light source is either visible or occluded





# Soft shadow creation



# Issues Affecting Shadows

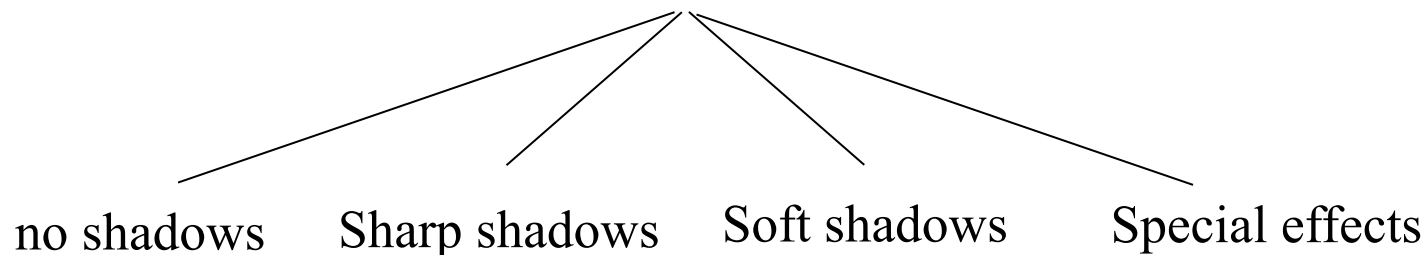


- Scene Complexity
  - Number of light sources
  - Types of light sources
  - Number of occluders
  - Number of receivers
  - Position, size and strength of lights
- Static vs. dynamic
  - Objects
  - Lighting
- Self-shadowing
- Opaque vs. transparent objects
- Precision or realism of shadows

# Current Shadow Methods



- There exist a very large number of methods
- We are interested in methods suitable for interactive walkthroughs, speed is crucial
- We will classify them on complexity:



# Sharp Shadows



- Point or directional light sources

Fake

Fast but often inadequate

- Billboard
- Projected object

Hardware Assisted

Use of specialized hardware to generate shadows

- Shadow texture
- Shadow volumes

Pre-computed

Shadows are pre-computed and stored for repeated use

- Detail polygons

Ray tracing

Rather slow for large scenes

# Soft Shadows



## ● Area light sources

### Hardware Assisted

Mainly treat the light source as a collection of points

- Accumulation buffer
- Shadow volumes
- Shadow textures

### Pre-computed

Mainly analytical computation on the geometry of the source

- Light maps
- Discontinuity Meshing

### Radiosity

This is also pre-computed

- Hemi-cube
- Ray casing

### Ray-based

- Distributed ray tracing
- Cone Tracing

# Approaches

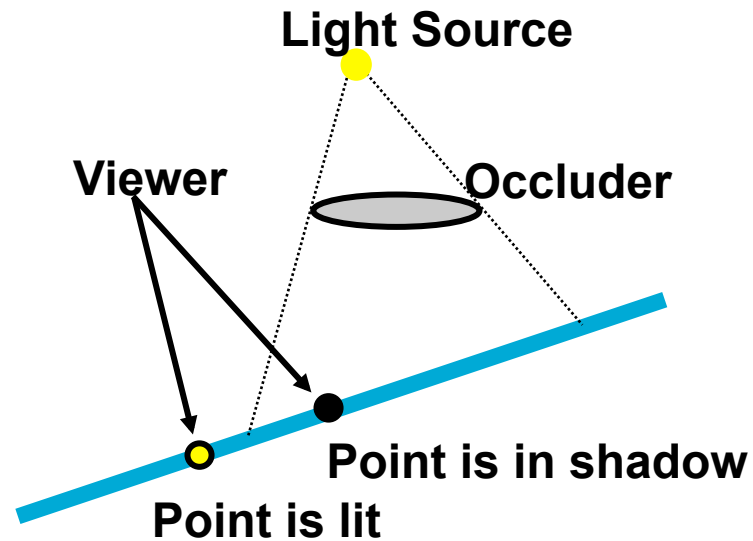


- **Ad-hoc / Custom**
  - Artist directed shadows
  - Very simple and constrained conditions.
- **Analytical**
  - Find all boundaries within the umbra / penumbra. Precise.
- **Sampling**
  - Probabilistic sampling of whether a particular fragment is within the umbra / penumbra. With enough samples can be made precise.

# Shadows and Illumination



- Given a point is in shadow, how do we change the illumination?



# Shadows and Illumination



- Illumination model with included visibility term:

$$I = k_a I_a + \sum_{i=1}^N V_i I_{l_i} (k_d \max(0, \mathbf{n} \cdot \mathbf{l}_i) + k_s \max(0, \mathbf{v} \cdot \mathbf{r}_i)^n)$$

For all lights

Visibility Term: 0 or 1 for  
point/directional lights

- Visibility term determines if a light can “see” the point
- If point is in shadow, only ambient term applies



# Shadows and OpenGL



- In OpenGL we send the geometry for a model through the pipeline.
- The Visibility function,  $V$ , is not a constant in our illumination model.
  - Per vertex information?
  - Per fragment using a texture map?
  - Some per-pixel masking function?
- Recall that we need a  $V$  for each light.

# Shadows and Illumination



- Note, we can re-write our illumination equation:

$$\begin{aligned} I &= k_a I_a + \sum_{i=1}^N V_i I_{l_i} \overbrace{(k_d \max(0, \mathbf{n} \cdot \mathbf{l}_i) + k_s \max(0, \mathbf{v} \cdot \mathbf{r}_i))^n}^{c_i} \\ &= k_a I_a + \sum_{i=1}^N V_i I_{l_i} c_i \\ &= k_a I_a + \sum_{i=1}^N [I_{l_i} c_i - (1 - V_i) I_{l_i} c_i] \end{aligned}$$

- Negative light.

# Masking in OpenGL



- OpenGL provides several ways of *masking* pixels
  - Stencil buffer with stencil test
  - Alpha test with fragment's alpha values
  - Blending with fragment's and framebuffer's alpha values.
  - Texture sampling and shaders.

# Negative Light



- Algorithm (single light)
  - Render receivers with full illumination
  - For each occluder
    - Project occluder from the light to the receivers
    - Darken (set to black or ambient) the illumination.

# Negative Light



- With multiple light sources this technique does not work. If the algorithm simply sets the pixels to black (or ambient), then it will erase the contributions from all light sources.

# Positive Light



- Algorithm
  - Render scene with ambient illumination only
  - For each light source
    - Render scene with illumination from this light only
    - Scale illumination by shadow mask
    - Add contribution to frame buffer